Feynman's ratchet and timecrystalline molecular motors

Antti Niemi

(with Cezary Czaplewski, Jin Dai, Adam Liwo, Xubiao Peng, Maciej Pyrka, Jianwei Wang, Frank Wilczek)



(Bio)molecular motors:

- Sustainable and often highly sophisticated performance
- Move autonomously and continuously often without external control
- Harvest resources directly from environment
- Stability often poor
- Motion often maintained under narrowly defined conditions

<u>Challenge</u> to design synthetic and artificial molecular machines with a comparable control of motion and function



Maxwell's Demon, Schrödinger's Cat ...

Feynman's ratchet-and-pawl:

PAWL

SPRING

 T_2

Gold Standard

Underlying assumptions:

- Rigid body
- External torque
- Non-equilibrium $(T_1 \neq T_2)$
- Broken symmetry (chirality)
- Driven by Brownian motion



Paradigm:

A functional molecular motor must know how to go around Feynman's No-Go arguments





What Feynman did not consider:

- Deformable bodies can have rotational motion even with no angular momentum
- Energy conserving system can be in motion even in the minimum of free energy

Going around Feynman:



Initially equilateral triangle with harmonically oscillating bond lengths



$$\mathcal{L} = \sum_{a=2,3} \left\{ \frac{1}{2} \left(\frac{dD_{1a}}{dt} \right)^2 - \frac{1}{2} \left(\frac{2\pi}{T_a} \right)^2 (D_{1a} - 1)^2 \right\}$$
$$D_{1a}(t) = 1 + a_{1a} \sin\left(\frac{2\pi}{T_a}t\right) \quad (a = 2, 3) \quad \& \quad D_{23} \equiv 1$$

rotational motion from change of shape:



$$\Delta \theta = \theta(T) - \theta(0) = \int_{0}^{T} dt \; \frac{\sum_{i=1}^{3} \left\{ s_{iy} \dot{s}_{ix} - s_{ix} \dot{s}_{iy} \right\}}{\sum_{i=1}^{3} \mathbf{s}_{i}^{2}} \equiv \int_{\Gamma} d\mathbf{l} \cdot \mathbf{A}$$

Three-body problem – Jacobi coordinates

$$egin{array}{rcl} \mathbf{s}_1&=&rac{1}{\sqrt{2}}oldsymbol{
ho}_1-rac{1}{\sqrt{6}}oldsymbol{
ho}_2\ \mathbf{s}_2&=&\sqrt{rac{2}{3}}oldsymbol{
ho}_2\ \mathbf{s}_3&=&-rac{1}{\sqrt{2}}oldsymbol{
ho}_1-rac{1}{\sqrt{6}}oldsymbol{
ho}_2 \end{array}$$

Dirac monopole in space of shapes

$$\mathbf{A} = \frac{1}{2}\cos\vartheta d\phi_{-} - \frac{1}{2}d\phi_{-} = \frac{1}{2}\frac{xdy - ydx}{r(r+z)}$$

= Connection in the shape space

$$\boldsymbol{\rho}_1 = r\cosrac{\vartheta}{2} \begin{pmatrix} \cos\phi_1\\ \sin\phi_1 \end{pmatrix} \quad \& \quad \boldsymbol{\rho}_2 = r\sinrac{\vartheta}{2} \begin{pmatrix} \cos\phi_2\\ \sin\phi_2 \end{pmatrix}$$

$$x = r \sin \vartheta \cos \phi_{-}$$
$$y = r \sin \vartheta \sin \phi_{-}$$
$$z = r \cos \vartheta$$

Physical example: cyclopropane

The CHARMM22 force field has the following potential energy function:^[7]

 $V = \sum_{bonds} k_b (b - b_0)^2 + \sum_{angles} k_ heta (heta - heta_0)^2 + \sum_{dihedrals} k_\phi [1 + cos(n\phi - \delta)]
onumber \ + \sum_{impropers} k_\omega (\omega - \omega_0)^2 + \sum_{Urey-Bradley} k_u (u - u_0)^2
onumber \ + \sum_{nonbonded} \left(\epsilon \left[\left(rac{R_{min_{ij}}}{r_{ij}}
ight)^{12} - \left(rac{R_{min_{ij}}}{r_{ij}}
ight)^6
ight] + rac{q_i q_j}{\epsilon r_{ij}}
ight)$

10 microsecond trajectory:





Microcanonical – no pawl It still appears to rotate



Rotational motion with no angular momentum
 Rotational motion even in lowest energy ground state
 Role of broken symmetry – broken parity

Rotation without angular momentum:

Guichardet 1984:

For three or more point-like particles, vibrations are continuously connected to rotations

Shapere & Wilczek 1987:

Connection in the space of shapes governs parallel transport: Periodic shape oscillation = closed trajectory

"Berry's phase"

Propose:

Connection in shape space combines and organizes individual atom thermal oscillations into a collective rotational motion of the entire molecule

Universality:

$$egin{aligned} V &= \sum_{bonds} k_b (b-b_0)^2 + \sum_{angles} k_ heta (heta- heta_0)^2 + \sum_{dihedrals} k_\phi [1+cos(n\phi-\delta)] \ &+ \sum_{impropers} k_\omega (\omega-\omega_0)^2 + \sum_{Urey-Bradley} k_u (u-u_0)^2 \ &+ \sum_{nonbonded} \left(\epsilon \left[\left(rac{R_{min_{ij}}}{r_{ij}}
ight)^{12} - \left(rac{R_{min_{ij}}}{r_{ij}}
ight)^6
ight] + rac{q_i q_j}{\epsilon r_{ij}}
ight) \end{aligned}$$

$$\mathcal{L} = \sum_{a=2,3} \left\{ \frac{1}{2} \left(\frac{dD_{1a}}{dt} \right)^2 - \frac{1}{2} \left(\frac{2\pi}{T_a} \right)^2 (D_{1a} - 1)^2 \right\}$$
$$D_{1a}(t) = 1 + a_{1a} \sin\left(\frac{2\pi}{T_a}t\right) \quad (a = 2, 3) \quad \& \quad D_{23} \equiv 1$$



After Feynman ...

"Bizarre forms of matter called time crystals were supposed to be physically impossible. Now they're not."



definition:

A material system is in a time crystal state when at the minimum of its free energy it can not be at rest but moves periodically.

propose:

Time crystal dynamics explains the impressive effectiveness of (bio)molecular motors, why they rotate apparently effortlessly even in highly viscous ambient water.



PARADIGM:

"A time crystal never reaches thermal equilibrium, as it is a type of nonequilibrium matter, a form of matter proposed in 2012, and first observed in 2017. This state of matter cannot be isolated from its environment—it is an open system in nonequilibrium."

<u>Counterexample</u>: *Hamiltonian with condition*



Critical point:

· Expetignization:

Minimize energy
 critical point of H

Hamilton's equation:

$$\begin{split} \delta H &= 0 \quad \Leftrightarrow \\ \begin{bmatrix} \partial H / \partial p^i &= -\dot{q}^i = 0 \\ \partial H / \partial q^i &= \dot{p}^i = 0 \end{split}$$

No "time crystal"

Constrained

- Energy H and set of <u>conditions</u> $G^a = 0$
- Minimize energy *H* subject to <u>conditions</u>

$$\Rightarrow \quad \text{Critical point of } H + \lambda^a G^a$$

$$\begin{array}{ll} -\partial H/\partial p^{i} = \lambda^{a} \partial G^{a}/\partial p^{i} & \equiv \lambda^{a} \{G^{a}, q^{i}\} = \dot{q}^{i} \\ -\partial H/\partial q^{i} = \lambda^{a} \partial G^{a}/\partial q^{i} & \equiv \lambda^{a} \{G^{a}, p^{i}\} = -\dot{p}^{a} \\ G^{a} = 0 & \end{array}$$

Solution (p^*, q^*, λ^*) $\lambda^* \neq 0 \implies \text{time crystal}$

Time evolution = symmetry transformation



"all possible molecular motions except bond stretching – shrinking"

Lie-Poisson bracket:

$$\{n_i^a, n_j^b\} = \pm \epsilon^{abc} \delta_{ij} n_i^c \qquad \mathbf{n} = \begin{pmatrix} \cos \varphi \sin \theta \\ \sin \varphi \sin \theta \\ \cos \theta \end{pmatrix} =$$

 $\{\cos\theta,\varphi\}=1$

Kirchhoff: Elastic rod in viscous fluid

Preserves bond length:

 $\{\mathbf{n}_i, \mathbf{n}_j \cdot \mathbf{n}_j\} = 0$ (for all i, j)

Examples of Hamiltonian time crystal:

$$\{t_i^a, t_j^b\} = \epsilon^{abc} \delta_{ij} t_i^c$$
$$\dot{\mathbf{t}}_i = \mathbf{t}_i \times \frac{\partial H}{\partial \mathbf{t}_i}$$

... when the equation

Condition:
$$\frac{d}{dt} \left(\sum_{i=1}^{N} \mathbf{t}_i \right) = \left(\sum_{i=1}^{N} \mathbf{t}_i \times \frac{\partial}{\partial \mathbf{t}_i} \right) H \Rightarrow \mathbf{G} \equiv \sum_{i=1}^{N} \mathbf{t}_i = 0$$

An initially closed chain remains closed provided Hamiltonian rotation invariant

Examples:

$$H = \sum_{\substack{i=1\\N}}^{N} a_i \mathbf{t}_i \cdot \mathbf{t}_{i+1}$$
$$H = \sum_{\substack{i=2\\i=2}}^{N} b_i \mathbf{t}_i \cdot (\mathbf{t}_{i-1} \times \mathbf{t}_{i+1})$$



has no time independent minimum energy solution

 $\{n_i^a, n_j^b\} = \epsilon^{abc} \delta_{ij} n_i^c$ $H = \sum a_i \, \mathbf{n}_i \cdot \mathbf{n}_{i+1}$ $\{H, \sum \mathbf{n}_i\} = 0$ Conserved: i=1N $\sum \mathbf{n}_i = 0$ closed chain i=1**Condition:** $\mathbf{n}_{N+1} = \mathbf{n}_1$ i=1 n_2 N=3: Equilateral triangle $H = \mathbf{n}_1 \cdot \mathbf{n}_2 + \mathbf{n}_2 \cdot \mathbf{n}_3 - \mathbf{n}_3 \cdot \mathbf{n}_1$ n₃ $\frac{d\mathbf{n}_1}{dt} = \mathbf{n}_1 \times (\mathbf{n}_2 - \mathbf{n}_3) \neq 0$ n_1 $\frac{d\mathbf{n}_2}{dt} = \mathbf{n}_2 \times (\mathbf{n}_3 + \mathbf{n}_1) = 0$ $\frac{d\mathbf{n}_3}{dt} = \mathbf{n}_3 \times (-\mathbf{n}_1 + \mathbf{n}_2) \neq 0$ **Time crystal** sum up: $\frac{d}{dt}(\mathbf{n}_1 + \mathbf{n}_2 + \mathbf{n}_3) = 0$

$$H_1 = \sum_{i=1}^3 a_i \mathbf{n}_i \cdot \mathbf{n}_{i+1}$$

$$H_2 = b\mathbf{n}_1 \cdot \mathbf{n}_2 \times \mathbf{n}_3 \qquad \qquad H_1 + H_2$$





Long range interactions

$$\mathbf{r}_i - \mathbf{r}_j = \mathbf{n}_i + ... + \mathbf{n}_{N^j-1}$$

Distance preserves chain closure: $\{\sum_{k=1}^{N} \mathbf{n}_k, |\mathbf{r}_i - \mathbf{r}_j|\} = 0$



Eμ

0

Trefoil knot as a Hamiltonian time crystal- part 1



Example:

Long Range Interactions

$$U(\mathbf{x}_1, \dots, \mathbf{x}_{12}) = \frac{1}{2} \sum_{\substack{i,j=1\\i \neq j}}^{12} \frac{1}{|\mathbf{x}_i - \mathbf{x}_j|} + \frac{1}{2} \sum_{\substack{i,j=1\\i \neq j}}^{12} \left(\frac{3/4}{|\mathbf{x}_i - \mathbf{x}_j|} \right)^{12}$$





UNRES simulation of V-ATPase rotor in *Enterococcus hirae* (PDB: 2BL2)









Summary:

- Deformable bodies can rotate without angular momentum*
- Deformable bodies can display timecrystalline dynamics even in lowest energy ground state*
- Simulations show promise for molecular motor function



*Feynman did not know

